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Atlas Refinement with Bounded Packing Efficiency

Presented by Jerry Yin



Packing efficiency

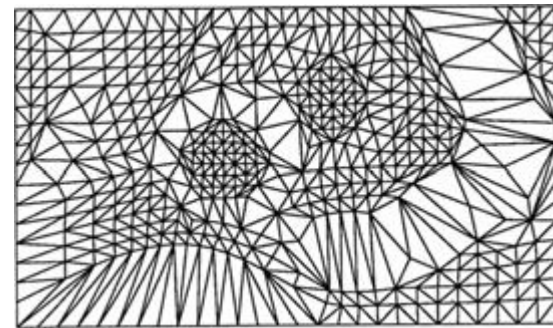
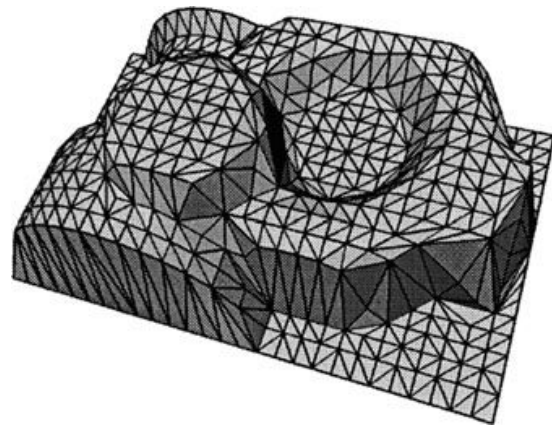
- Store high-frequency information in rectangular 2D texture images.
- Textures are mapped to 3D surfaces using UV coordinates.
- Unused parts of the image are wasted
- A *texture atlas* is composed of *charts*.
- *Packing efficiency* is
$$\text{area(atlas)} / \text{area(atlas bounding box)}.$$



Model by
Geoffrey Marchal.

Packing problem

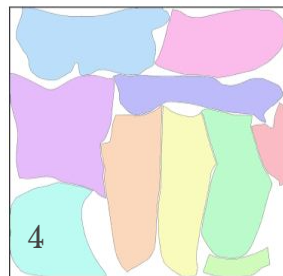
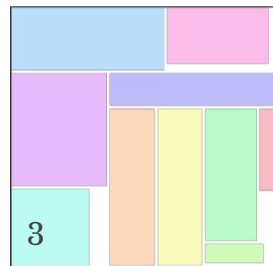
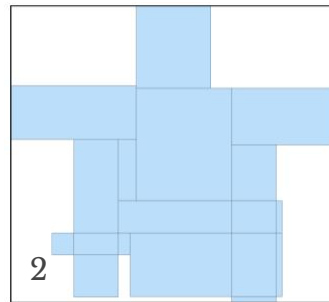
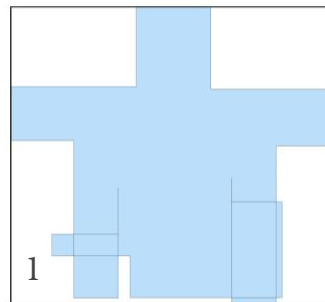
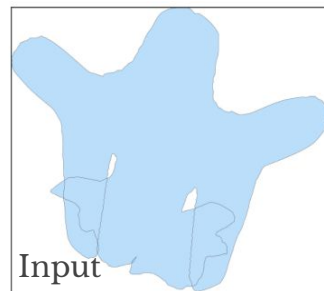
- Fixed boundary parameterization can give perfect packing efficiency, but has high distortion.
- Making each triangle its own chart gives zero distortion *and* good packing efficiency, but leads to poor performance and potential artifacts.
- We want
 - high packing efficiency,
 - low distortion, *and*
 - short boundaries.



Algorithm overview

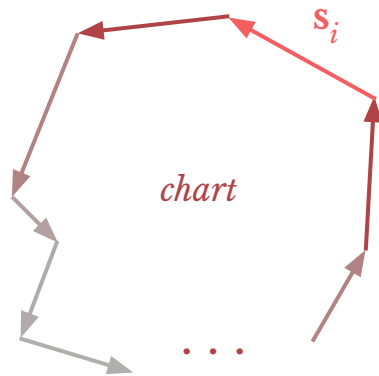
Given an existing texture atlas:

1. Deform input charts so that their boundaries are axis-aligned.
2. Cut axis-aligned charts into rectangles.
3. Pack rectangles.
4. Relax boundaries of rectangles to reduce distortion.



Axis-aligned boundaries

- Want to make boundary edges of all charts axis-aligned.
- To minimize corners, (Gaussian) smooth direction of all boundary edges.
 - Each direction is repeatedly set to weighted average of neighbourhood's directions.
- Find optimally axis-aligned rotation R of each chart by optimizing $\min_R \sum \|\mathbf{s}_i\| \Phi(R\mathbf{s}_i)$
where $\Phi(x, y) = x^2 y^2$

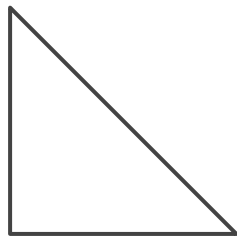


Aside: Gauss-Bonnet theorem

- α_i : interior angle at vertex i

$$\sum_i (\pi - \alpha_i) = 2\pi$$

- Corollary: if we increase the interior angle somewhere, we must decrease it by an equivalent amount somewhere else (possibly in multiple places).



$$\left(\pi - \frac{\pi}{2}\right) + \left(\pi - \frac{\pi}{4}\right) + \left(\pi - \frac{\pi}{4}\right) = 2\pi$$



$$4 \left(\pi - \frac{\pi}{2}\right) = 2\pi$$

Axis-aligned boundaries (cont'd)

- $\Gamma(\mathbf{s}_i)$: closest axis direction to \mathbf{s}_i
- Update each interior angle α_i to be

$$\alpha_i + \angle(\mathbf{s}_i, \Gamma(\mathbf{s}_i)) - \angle(\mathbf{s}_{i+1}, \Gamma(\mathbf{s}_{i+1}))$$

- Result may have foldovers ($\alpha_i \leq 0$).
 - Find boundary verts ($\alpha_j = 180^\circ$) adjacent to α_i , and set $\alpha_j = 90^\circ$ and add 90° to α_i .
- More optimizations: corners can be merged or moved sometimes to reduce distortion.

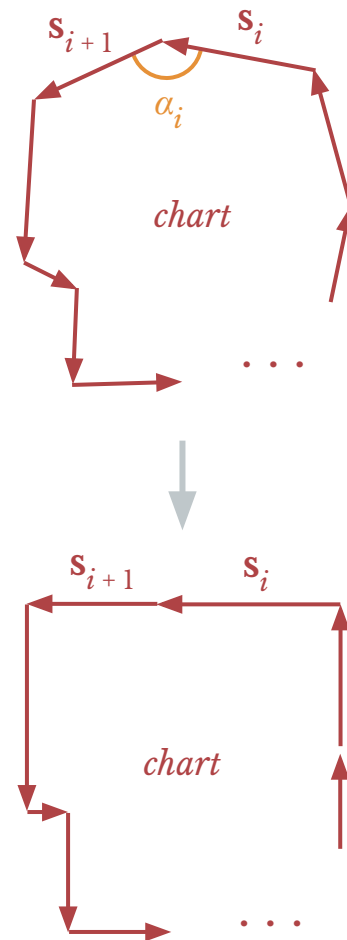


Chart deformation

$$E_{\text{edge}}(\mathbf{b}_i) = \frac{1}{2}(1 - \gamma)(\theta_i - \frac{\pi}{2}\Theta_i)^2 + \frac{1}{2}\gamma(\frac{l_i}{l_i^0} - 1)^2$$

$$E_{\text{align}}(\mathbf{c}) = \sum_{i=1}^{N_b} \frac{l_i^0}{l^0} E_{\text{edge}}(\mathbf{b}_i),$$

preserve
already
obtained angles

preserve
lengths

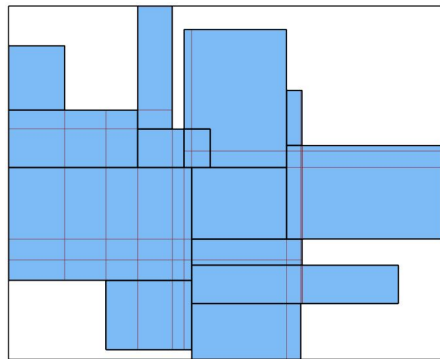
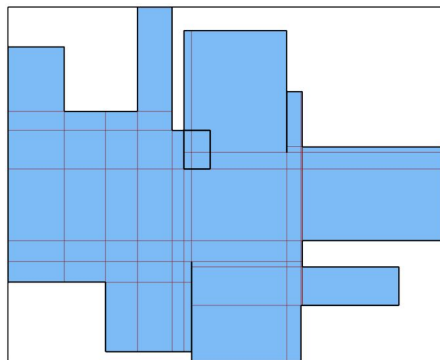
weight according
to length

- Interior vertices need to be adjusted.
- Minimize sum of $E_{\text{align}}(\mathbf{c})$ (to get close-to-axis-aligned boundaries) and symmetric Dirichlet energy (to minimize isometric distortion) for chart \mathbf{c} .
 - Increasingly prioritize $E_{\text{align}}(\mathbf{c})$ as we iterate.

Afterwards, snap the result to be exactly axis-aligned.

Cutting charts with motorcycles

- *Motorcycle* starts at a corner and travels in a straight axis-aligned line, and stops when it hits a boundary or the trail of a different motorcycle.
- For each two consecutive interior edges of a corner, at least one edge must be assigned a motorcycle in order to get a rectangular partition [Eppstein et al. 2008].
- Partition not unique (choice of motorcycle assignment and ordering).

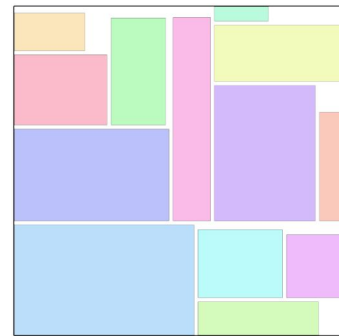
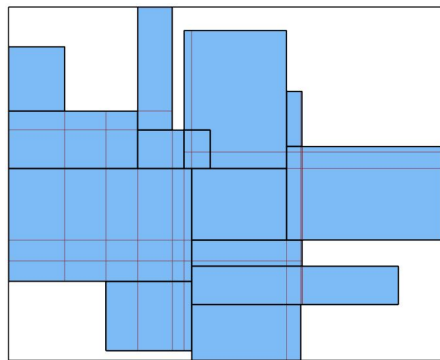


Cutting charts with motorcycles (cont'd)

- Generate motorcycle decompositions at random.
- Pack rectangles with small padding around boundary (useful later).
- Evaluate each packing with score

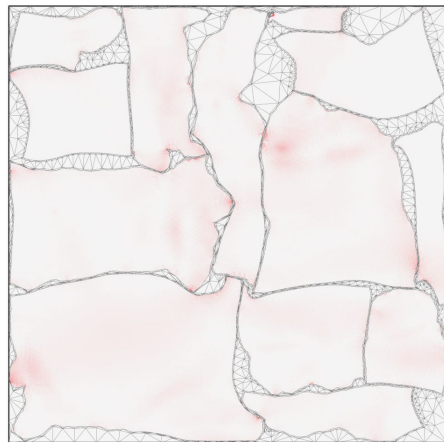
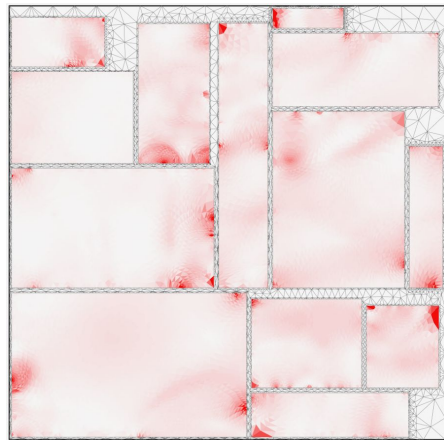
$$\text{packing efficiency} = \omega \frac{\text{boundary len after cut}}{\text{boundary len before cut}}$$

- Pick one with highest score.

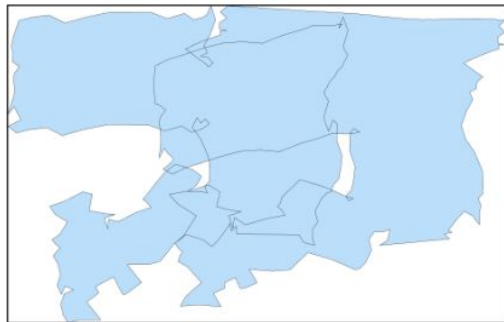


Relaxing the boundaries

- Based on scaffolding method [Jiang et al. 2017].
 - Triangulate empty space, then minimize symmetric Dirichlet energy.
- Allows maintaining padding around charts.
 - Useful for subsequent applications.



Results



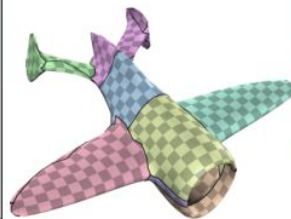
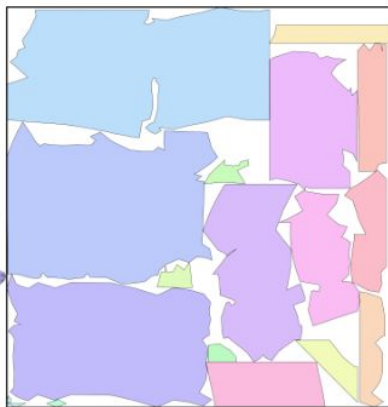
Aircraft

BL = 7.58
 $E_d = 1.149$



Box Cutter

PE = 81.1% $E_d = 1.149$
BL = 11.19 $E_2 = 1.000$
 $N_{<3\%} = 12$ SAE = 0.0034
SA = 0.006% 179.8 seconds

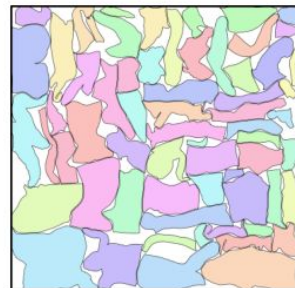
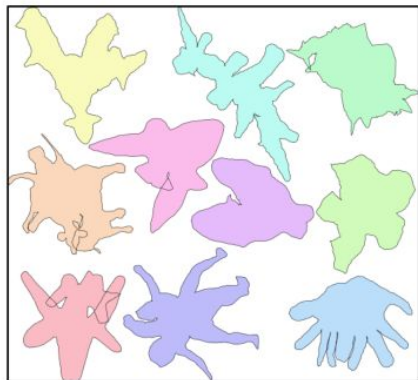
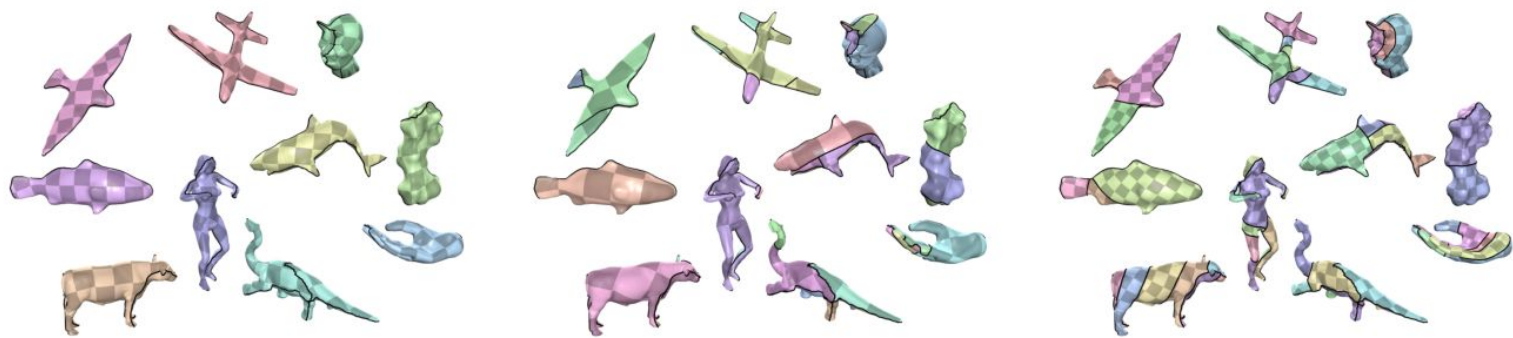


Ours

PE = 88.9% $E_d = 1.087$
BL = 10.70 $E_2 = 1.135$
 $N_{<3\%} = 1$ SAE = 0.0032
SA = 1.41% 1.69 seconds



Results

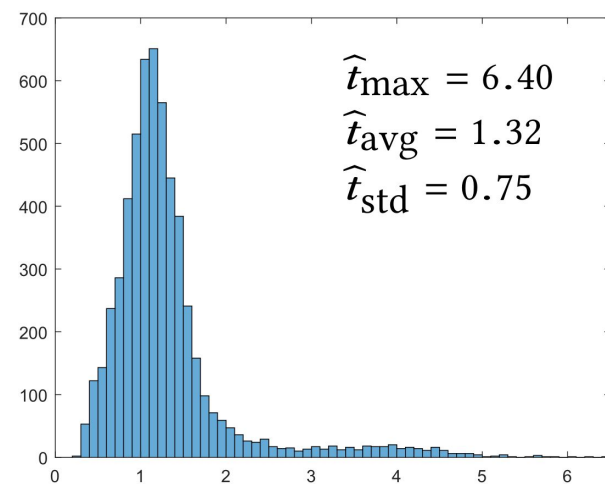


	PE = 69.9%	PE = 80.0%
	SA = 0.0002%	SA = 0.15%
	$N_{<3\%} = 52$	$N_{<3\%} = 57$
BL = 14.42	BL = 19.79	BL = 22.79
$E_d = 1.022$	$E_d = 1.022$	$E_d = 1.026$
	$E_2 = 1.000$	$E_2 = 1.019$

Input

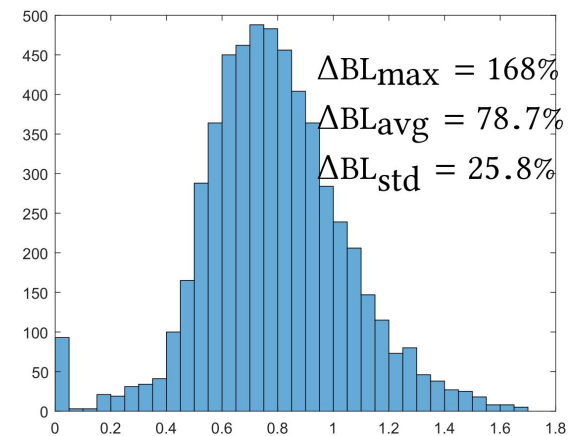
Box Cutter

Ours



Timings
(runtime (ms?) / # vertices).

Boundary length
elongation.



Isometric distortion
w/r/t original mesh.

Isometric distortion
w/r/t input atlas.

